Q4X Stainless Steel Analog Laser Sensor Product Manual

Original Instructions
p/n: 185624 Rev. I
24-Jul-25
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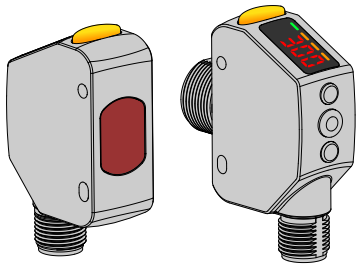
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Chapter 1 Product Description

Class 1 laser CMOS analog sensor with an analog output. Patent pending.



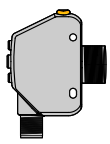
- Reliably detects submillimeter distance changes
- Continuous measurement of challenging targets from dark to reflective, out to 500 mm (threaded barrel models) or 310 mm (flush mount models), depending on model
- Resists mechanical impact, over tightening, and extreme vibration
- Simplified user experience with analog (V or mA) or distance (mm) readout from the angled, four-digit display
- Easy setup with responsive buttons
- Durable and robust construction resists mechanical impact, over tightening, and extreme vibration
- FDA grade stainless steel, rated to IP67, IP68, and IP69K, ECOLAB® certified chemically-resistant materials, and laser marked sensor information withstands aggressive cleaning procedures
- Superior ambient light resistance

For illustration purposes, the threaded barrel model Q4X images are used throughout this document.

WARNING:

- **Do not use this device for personnel protection**
- Using this device for personnel protection could result in serious injury or death.
- This device does not include the self-checking redundant circuitry necessary to allow its use in personnel safety applications. A device failure or malfunction can cause either an energized (on) or de-energized (off) output condition.

Models

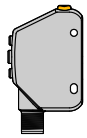
Model		Sensing Range	Output	Connection[1]
	Q4XTULAF600-Q8	25 mm to 600 mm (0.98 in to 23.62 in)	Analog voltage (0 to 10 V)	Integral 5-pin M12 male quick-disconnect connector
	Q4XTILAF600-Q8		Analog current (4 to 20 mA)	
	Q4XTULAF500-Q8	25 mm to 500 mm (0.98 in to 19.68 in)	Analog voltage (0 to 10 V)	
	Q4XTILAF500-Q8		Analog current (4 to 20 mA)	
	Q4XTULAF300-Q8	25 mm to 300 mm (0.98 in to 11.81 in)	Analog voltage (0 to 10 V)	
	Q4XTILAF300-Q8		Analog current (4 to 20 mA)	
	Q4XTULAF100-Q8	25 mm to 100 mm (0.98 in to 3.94 in)	Analog voltage (0 to 10 V)	
	Q4XTILAF100-Q8		Analog current (4 to 20 mA)	

Continued on page 5

[1] QD models require a mating cordset.

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Continued from page 4

Model		Sensing Range	Output	Connection
	Q4XFULAF610-Q8	35 mm to 610 mm (1.38 in to 24.02 in)	Analog voltage (0 to 10 V)	
	Q4XFILAF610-Q8		Analog current (4 to 20 mA)	
	Q4XFULAF310-Q8	35 mm to 310 mm (1.38 in to 12.20 in)	Analog voltage (0 to 10 V)	
	Q4XFILAF310-Q8		Analog current (4 to 20 mA)	
	Q4XFULAF110-Q8	35 mm to 110 mm (1.38 in to 4.33 in)	Analog voltage (0 to 10 V)	
	Q4XFILAF110-Q8		Analog current (4 to 20 mA)	

Overview

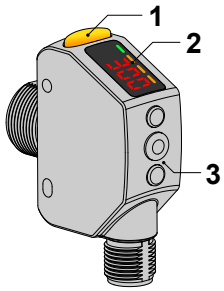
The Q4X Analog Sensor is a Class 1 laser CMOS measuring sensor that uses a 0 to 10 V (4 to 20 mA) output to represent the distance measured.

When the sensor is in Run mode, the display shows the current measurement reading or corresponding analog output value. The size and location of the analog output window can be manually adjusted or the selected TEACH method can be performed.

When the sensor is in Setup mode, all standard operating parameters, including TEACH mode, analog slope, response time, and more can be adjusted, or a factory reset can be performed.

Features

Sensor Features

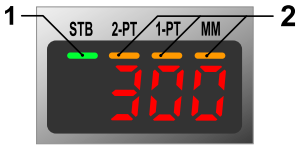


1. Output Indicator (Amber)
2. Display
3. Buttons

Display and Indicators

The display is a 4-digit, 7-segment LED. The main screen is the Run Mode screen, which shows the current distance to the target in millimeters.

Display in Run Mode



1. Stability Indicator (STB = Green)
2. Active TEACH Indicators
   - 2-PT = Two-Point TEACH (Amber)
   - 1-PT = One-Point TEACH (Amber)
3. Display Value Indicator (MM = Amber)

Output Indicator

- On—Displayed distance is within the taught analog output window
- Off—Displayed distance is outside of the taught analog output window

Active TEACH Indicators (2PT and 1PT)

- 2-PT on—Two-point TEACH mode selected (default)
- 1-PT on—One-point TEACH mode selected

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Stability Indicator (STB)

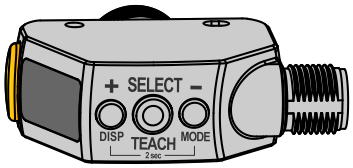
- On—Stable signal within the specified sensing range
- Flashing—Marginal signal, the target is outside of the limits of the specified sensing range, or a multiple peak condition exists
- Off—No target detected within the specified sensing range

Display Value Indicator (MM)

- On—Display shows the distance in millimeters (default)
- Off—Display shows the analog output value

Buttons

Use the sensor buttons **(SELECT)(TEACH)**, **(+)(DISP)**, and **(-)(MODE)** to program the sensor.



(SELECT)(TEACH)

- Press and hold for longer than 2 seconds to start the currently selected TEACH mode (the default is two-point TEACH)
- Press to select menu items in Setup mode

(-)(MODE)

- Press to change the distance setting for the 0 V (4 mA) point; press and hold to decrease numeric values
- Press and hold for longer than 2 seconds to enter Setup mode
- Press to navigate the sensor menu in Setup mode

(+)(DISP)

- Press to change the distance setting for the 10 V (20 mA) point; press and hold to increase numeric values
- Press and hold for longer than 2 seconds to toggle the display value between the distance and the analog output
- Press to navigate the sensor menu in Setup mode

NOTE: When navigating the menu, the menu items loop.

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Chapter 2 Specifications

Sensing Beam
Visible red Class 1 laser, 655 nm

Supply Voltage (Vcc)
12 V DC to 30 V DC

Power and Current Consumption, exclusive of load
< 675 mW

Sensing Range—Threaded Barrel Models
600 mm models: 25 mm to 600 mm (0.98 in to 23.62 in)
500 mm models: 25 mm to 500 mm (0.98 in to 19.68 in)
300 mm models: 25 mm to 300 mm (0.98 in to 11.81 in)
100 mm models: 25 mm to 100 mm (0.98 in to 3.94 in)

Sensing Range—Flush Mount Models
610 mm models: 35 mm to 610 mm (1.38 in to 24.02 in)
310 mm models: 35 mm to 310 mm (1.38 in to 12.20 in)
110 mm models: 35 mm to 110 mm (1.38 in to 4.33 in)

Analog Output Configuration
0 V to 10 V or 4 mA to 20 mA, depending on model

Output Rating
Analog Voltage Outputs (Q4X..U Models): 2.5 kOhm minimum load resistance
Analog Current Outputs (Q4X..I Models): 1 kΩ maximum load resistance at 24 V; maximum load resistance = [(Vcc – 4.5)/ 0.02 Ω]

Remote Input
Allowable Input Voltage Range: 0 to Vcc
Active Low (internal weak pullup—sinking current): Low State < 2.0 V at 1 mA max.

Supply Protection Circuitry
Protected against reverse polarity and transient overvoltages

Analog Resolution—Threaded Barrel Models
300 mm and 600 mm models:
25 mm to 100 mm: < 0.3 mm
100 mm to 300 mm: < 1 mm
500 mm models only: 300 to 500 mm: < 1.75 mm
600 mm models only: 300 to 600 mm: < 2 mm
100 mm models: 25 mm to 100 mm: < 0.15 mm

Analog Resolution—Flush Mount Models
610 mm models: 310 to 610 mm: < 2 mm
310 mm models:
35 mm to 110 mm: < 0.3 mm
110 mm to 310 mm: < 1 mm
110 mm models: 35 mm to 110 mm: < 0.15 mm

Analog Linearity
Analog linearity performance matches accuracy performance curve (see "Performance Curves—Threaded Barrel Models" on page 11 and "Performance Curves—Flush Mount Models" on page 13).
On 600 mm and 610 mm models, linearity is the lesser of accuracy or 2.5% of full scale range

Response Speed
Total response speed varies from 0.5 ms to 2560 ms, depending on base measurement rate and averaging settings.
See for more information.

Delay at Power Up
< 750 ms

Ambient Light Immunity
> 5,000 lux at 300 mm
> 2,000 lux at 500 mm

Maximum Torque
Side mounting: 1 N·m (9 in·lbs)
Nose mounting: 20 N·m (177 in·lbs)

Connector
Integral 5-pin M12 male quick-disconnect connector

Construction
Housing: 316 L stainless steel
Lens cover: PMMA acrylic
Lightpipe and display window: polysulfone

Chemical Compatibility
Compatible with commonly used acidic or caustic cleaning and disinfecting chemicals used in equipment cleaning and sanitation. ECOLAB® certified.
Compatible with typical cutting fluids and lubricating fluids used in machining centers

Application Note
For optimum performance, allow 10 minutes for the sensor to warm up

Environmental Rating
IP67 per IEC60529
IP68 per IEC60529
IP69K per ISO 20653
IP rating is dependent on proper cordset installation.

Shock
MIL-STD-202G, Method 213B, Condition I (100G 6x along X, Y, and Z axes, 18 shocks), with device operating

Vibration
MIL-STD-202G, Method 201A (Vibration: 10 Hz to 60 Hz, 0.06 inch (1.52 mm) double amplitude, 2 hours each along X, Y and Z axes), with device operating

Storage Temperature
–25 °C to +75 °C (–13 °F to +167 °F)

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Beam Spot Size—100/110 mm Models

Beam Spot Size—100/110 mm Models

Distance (mm)		Size (Horizontal × Vertical)
Threaded Barrel Models	Flush Mount Models	
25	35	2.4 mm × 1.0 mm
50	60	2.2 mm × 0.9 mm
100	110	1.8 mm × 0.7 mm

Beam Spot Size—300/310 mm, 500 mm, and 600/610 Models

Beam Spot Size—300/310 mm, 500 mm, and 600/610 mm Models

Distance (mm)		Size (Horizontal × Vertical)
Threaded Barrel Models	Flush Mount Models	
25	35	2.6 mm × 1.0 mm
150	160	2.3 mm × 0.9 mm
300	310	2.0 mm × 0.8 mm
500	-	1.9 mm × 1.0 mm
600	610	1.9 mm × 1.0 mm

Excess Gain using a 90% White Card—600/610 mm Models

HIGH *Excess Gain (* Std *Excess Gain*[2]*)*

Response Speed (ms)	· at 25 mm (600 mm models) · at 35 mm (610 mm models)	· at 100 mm (600 mm models) · at 110 mm (610 mm models)	· at 300 mm (600 mm models) · at 310 mm (610 mm models)	· at 600 mm (600 mm models) · at 610 mm (610 mm models)
2	280	110	25	6
5	280	110	25	6
15	1000 (360)	400 (150)	80 (30)	20 (7)
25	2000 (1000)	800 (400)	160 (80)	40 (20)
50	4000 (2000)	1600 (800)	320 (160)	80 (40)

(2)

- Std *excess gain available in 15 ms response speed only*
- Std *excess gain provides increased noise immunity*

Operating Conditions

35% to 95% relative humidity

	Min. Ambient Temp (°C)	Max. Ambient Temp (°C)	
Vcc	All Models	Q4X…U (0–10V)	Q4X..I (4–20 mA)*
12	–10	50	50
24			45
30			40

* For 4–20 mA models only: Max. Ambient Sensor Temp (°C) = 50 – (Vcc – 12)/2

Required Overcurrent Protection

WARNING: Electrical connections must be made by qualified personnel in accordance with local and national electrical codes and regulations.

Overcurrent protection is required to be provided by end product application per the supplied table.

Overcurrent protection may be provided with external fusing or via Current Limiting, Class 2 Power Supply.

Supply wiring leads < 24 AWG shall not be spliced.

For additional product support, go to www.bannerengineering.com.

Supply Wiring (AWG)	Required Overcurrent Protection (A)	Supply Wiring (AWG)	Required Overcurrent Protection (A)
20	5.0	26	1.0
22	3.0	28	0.8
24	2.0	30	0.5

Certifications

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1831 Diegem, BELGIUM

Turck Banner LTD Blenheim House
Blenheim Court
Wickford, Essex SS11 8YT
GREAT BRITAIN

c UL us LISTED Industrial Control Equipment 3TJJ Class 2 power
UL Environmental Rating: Type 1

ECOLAB chemical compatibility certified
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Class 1 Laser Description and Safety Information



Laser light. Do not stare into the beam.

Complies with 21 CFR 1040.10 and 1040.11 except for deviations pursuant to Laser Notice No. 56, dated May 8, 2019.

CLASS 1
LASER PRODUCT

CAUTION:

- **Never stare directly into the sensor lens.**
- Laser light can damage your eyes.
- Avoid placing any mirror-like object in the beam. Never use a mirror as a retroreflective target.

CAUTION:

- **Return defective units to the manufacturer.**
- Use of controls or adjustments or performance of procedures other than those specified herein may result in hazardous radiation exposure.
- Do not attempt to disassemble this sensor for repair. A defective unit must be returned to the manufacturer.

Class 1 lasers are lasers that are safe under reasonably foreseeable conditions of operation, including the use of optical instruments for intrabeam viewing.

Complies with IEC 60825-1:2014 and EN 60825-1:2014+A11:2021.

For safe laser use:

- Do not stare at the laser.
- Do not point the laser at a person's eye.
- Mount open laser beam paths either above or below eye level, where practical.
- Terminate the beam emitted by the laser product at the end of its useful path.

Models with a Range of ≤ 510 mm

Class 1 Laser Characteristics

Output power < 0.20 mW
Laser wavelength: 655 nm
Pulse duration: 7 µs to 2 ms

Models with a Range of > 510 mm

Class 1 Laser Characteristics

Output power: < 0.39 mW
Laser wavelength: 655 nm
Pulse duration: 7 µs to 2 ms

FCC Part 15 Class B for Unintentional Radiators

(Part 15.105(b)) This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

(Part 15.21) Any changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate this equipment.

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Industry Canada ICES-003(B)

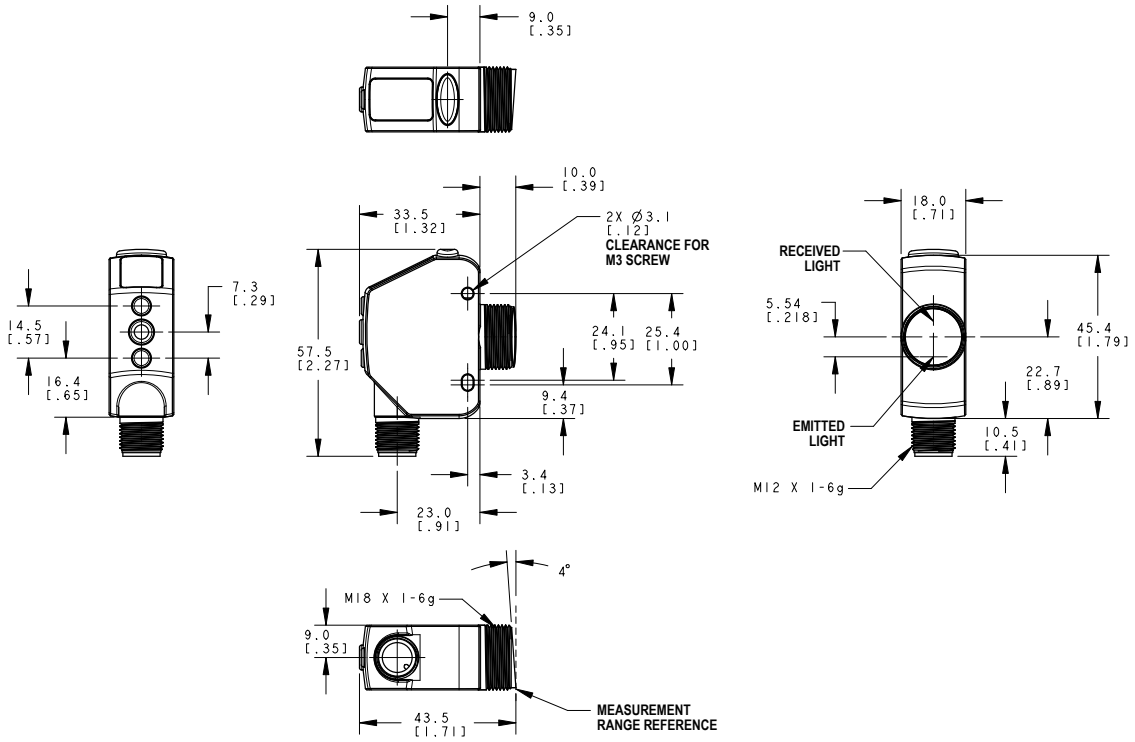
This device complies with CAN ICES-3 (B)/NMB-3(B). Operation is subject to the following two conditions: 1) This device may not cause harmful interference; and 2) This device must accept any interference received, including interference that may cause undesired operation.

Cet appareil est conforme à la norme NMB-3(B). Le fonctionnement est soumis aux deux conditions suivantes : (1) ce dispositif ne peut pas occasionner d'interférences, et (2) il doit tolérer toute interférence, y compris celles susceptibles de provoquer un fonctionnement non souhaité du dispositif.

Dimensions

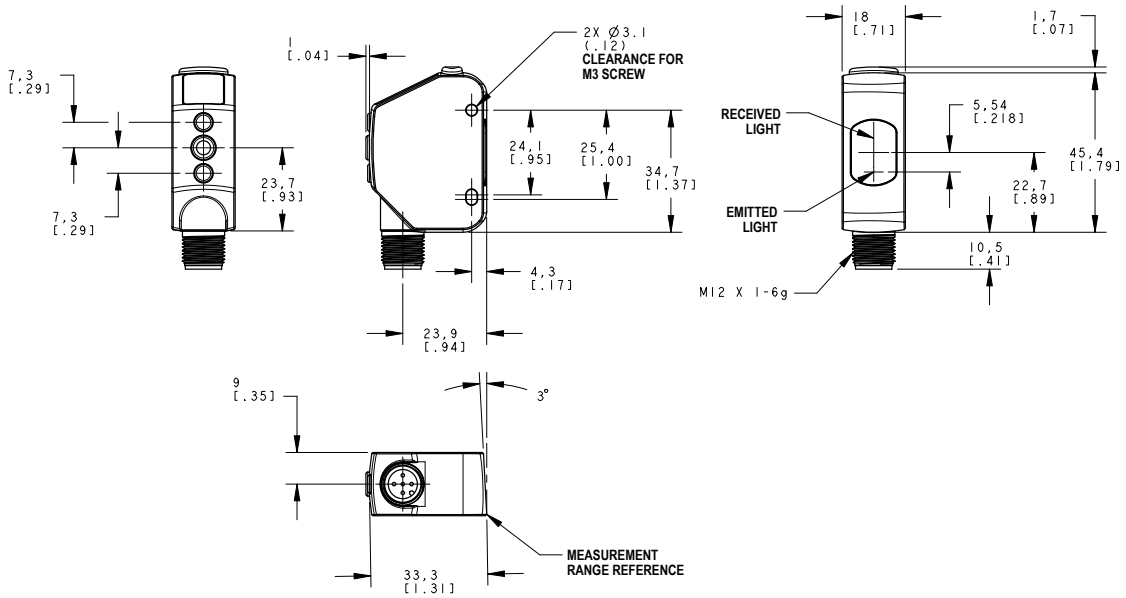
All measurements are listed in millimeters [inches], unless noted otherwise. The measurements provided are subject to change.

Threaded Barrel Models



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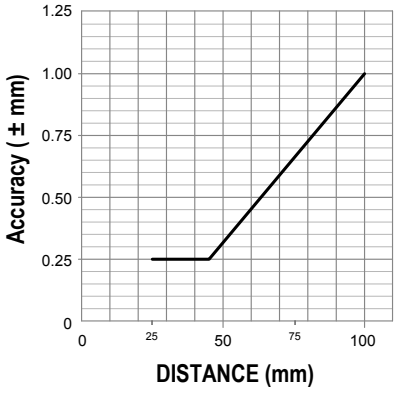
Flush Mount Models



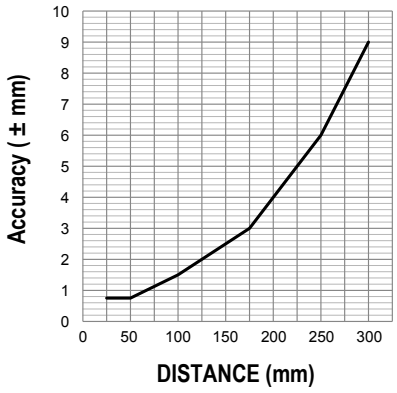
Performance Curves—Threaded Barrel Models

Accuracy (90% to 6% reflectance)

100 mm Models



300 mm Models



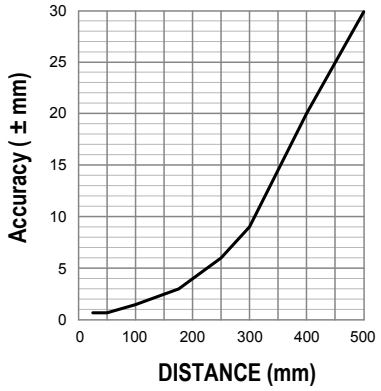
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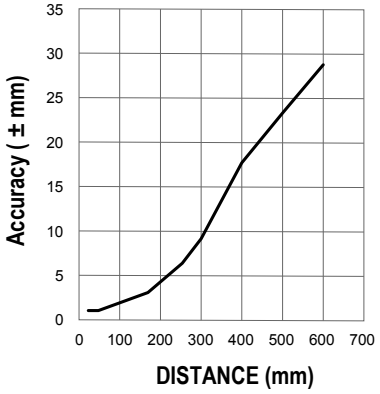
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Accuracy (90% to 6% reflectance)

500 mm Models

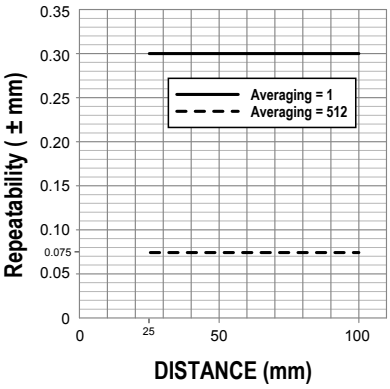


600 mm Models

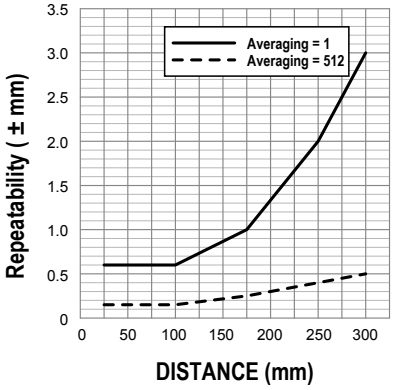


Repeatability (90% to 6% reflectance)

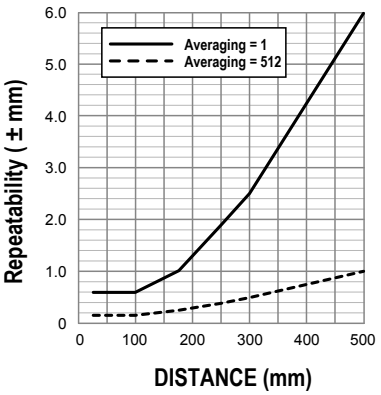
100 mm Models



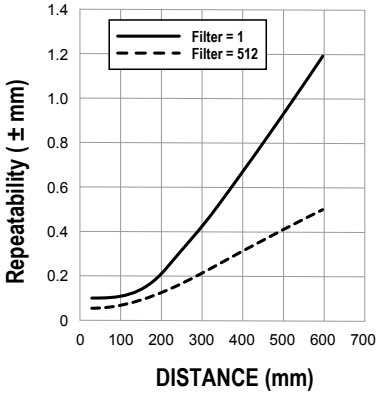
300 mm Models



500 mm Models



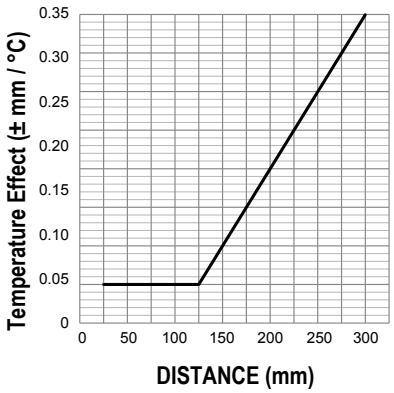
600 mm Models



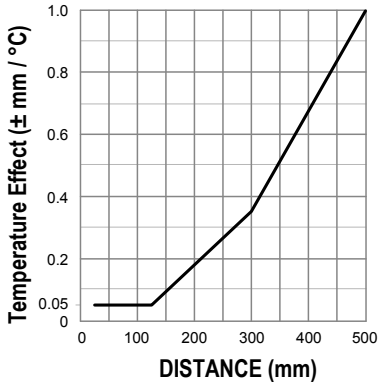
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Typical Temperature Effects[3]

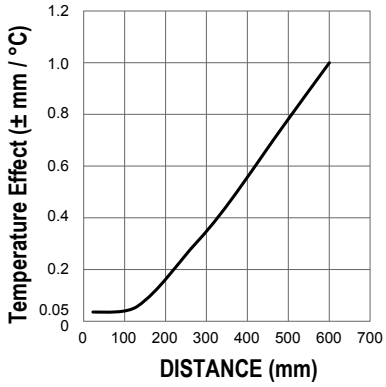
100 mm and 300 mm Models



500 mm Models



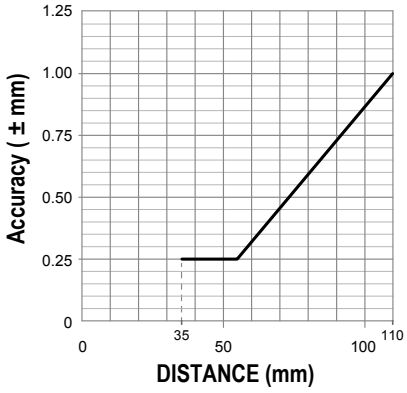
600 mm Models



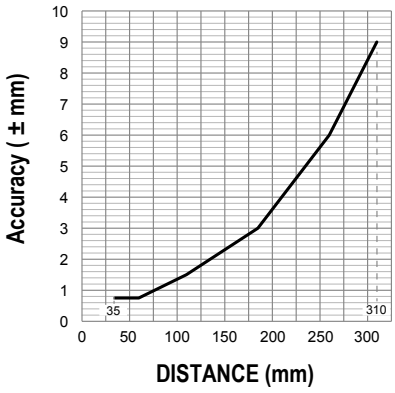
Performance Curves—Flush Mount Models

Accuracy (90% to 6% reflectance)

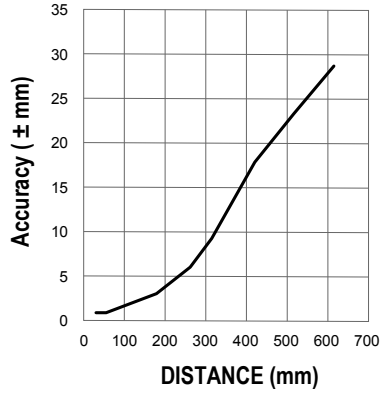
110 mm Models



310 mm Models



610 mm Models

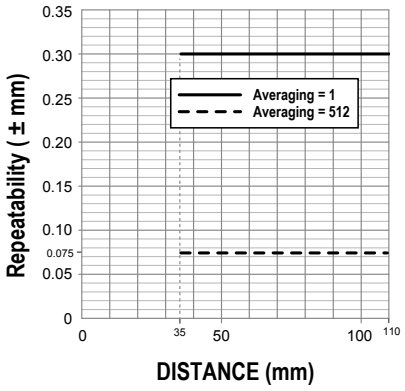


(3) Calculated as an average temperature effect across the sensor's full operating temperature.

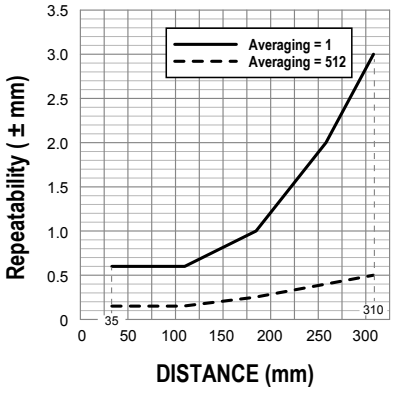
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Repeatability (90% to 6% reflectance)

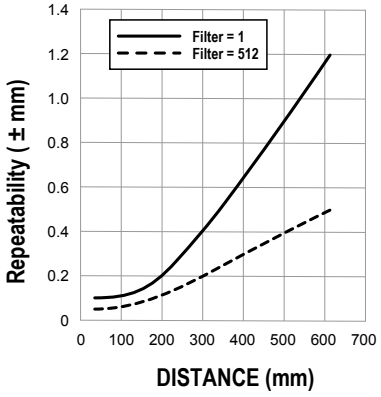
110 mm Models



310 mm Models

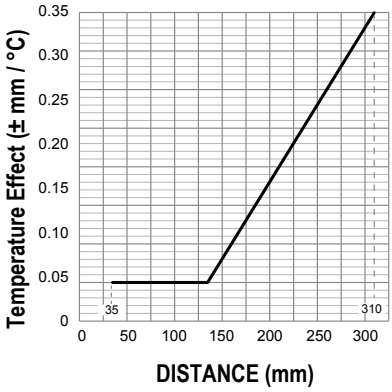


610 mm Models

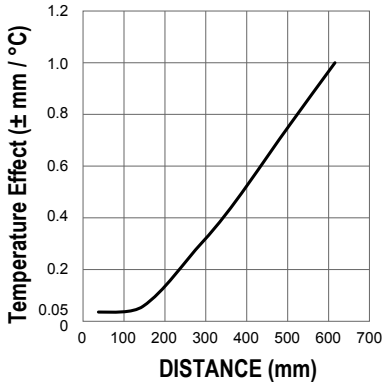


Typical Temperature Effects[4]

110 mm and 310 mm Models



610 mm Models



[4] Calculated as an average temperature effect across the sensor's full operating temperature.

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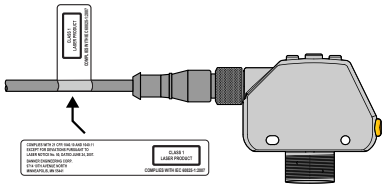
Install the Safety Label 15
Sensor Orientation 15
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Chapter 3 Installation

Install the Safety Label

The safety label must be installed on Q4X sensors that are used in the United States.

Safety Label Installation



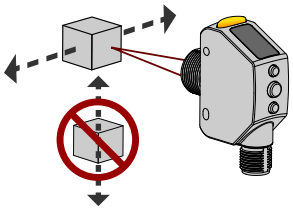
NOTE: Position the label on the cable in a location that has minimal chemical exposure.

1. Remove the protective cover from the adhesive on the label.
2. Wrap the label around the Q4X cable, as shown.
3. Press the two halves of the label together.

Sensor Orientation

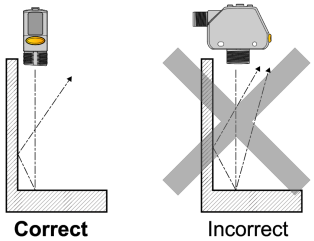
Optimize detection reliability and performance with correct sensor-to-target orientation. To ensure reliable detection, orient the sensor as shown in relation to the target to be detected.

Optimal Orientation of Target to Sensor

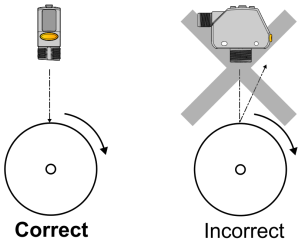


See the following figures for examples of correct and incorrect sensor-to-target orientation as certain placements may pose problems for sensing some targets.

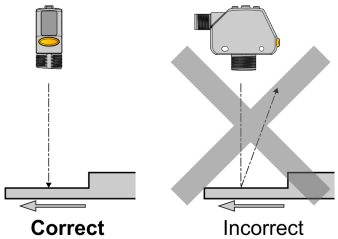
Orientation by a wall



Orientation for a turning object



Orientation for a height difference

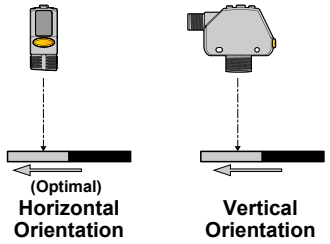


Continued on page 16

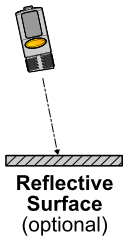
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Continued from page 15

Orientation for a color or luster difference



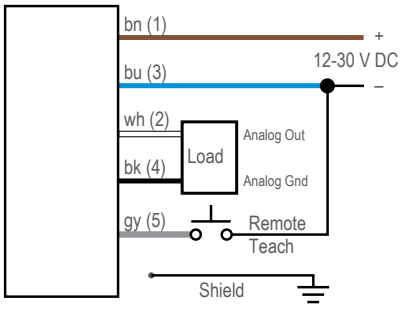
Orientation for highly reflective target[5]

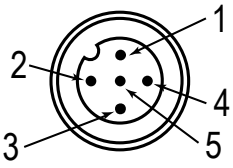


Mount the Device

1. If a bracket is needed, mount the device onto the bracket.
2. Mount the device (or the device and the bracket) to the machine or equipment at the desired location. Do not tighten the mounting screws at this time.
3. Check the device alignment.
4. Tighten the mounting screws to secure the device (or the device and the bracket) in the aligned position.

Wiring Diagram





Key

1 = Brown
2 = White
3 = Blue
4 = Black
5 = Gray

NOTE: Open lead wires must be connected to a terminal block.

NOTE: The input wire function is user-selectable. The default for the input wire function is off (disabled).

NOTE: Shielded cordsets are recommended for all models with quick disconnect fittings. It is recommended that the shield wire be connected to -V DC (the blue wire).

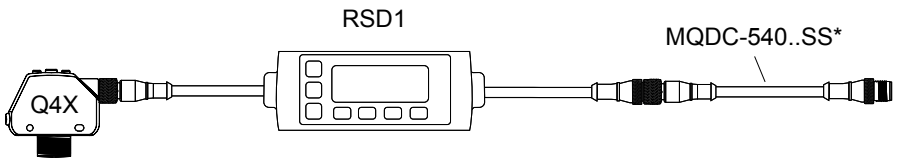
[5] *Applying tilt to sensor may improve performance on reflective targets. The direction and magnitude of the tilt depends on the application, but a 15° tilt is often sufficient.*

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Connecting to RSD1

The following diagram depicts the connection of the Q4XTULAF600, Q4XTILAF600, Q4XTULAF610, or Q4XTILAF610 to the optional RSD1 accessory.

Q4X to RSD1



**Optional Extension Cordset: MQDEC3-5..SS*

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Locking and Unlocking the Sensor Buttons 28
Button Instructions 29
Remote Input Instructions 29
TEACH Procedures 29
Sync Master/Slave 32

Chapter 4 Sensor Programming

Program the sensor using the buttons on the sensor or the remote input (limited programming options).

In addition to programming the sensor, use the remote input to disable the buttons for security, preventing unauthorized or accidental programming changes. See "Locking and Unlocking the Sensor Buttons" on page 28 for more information.

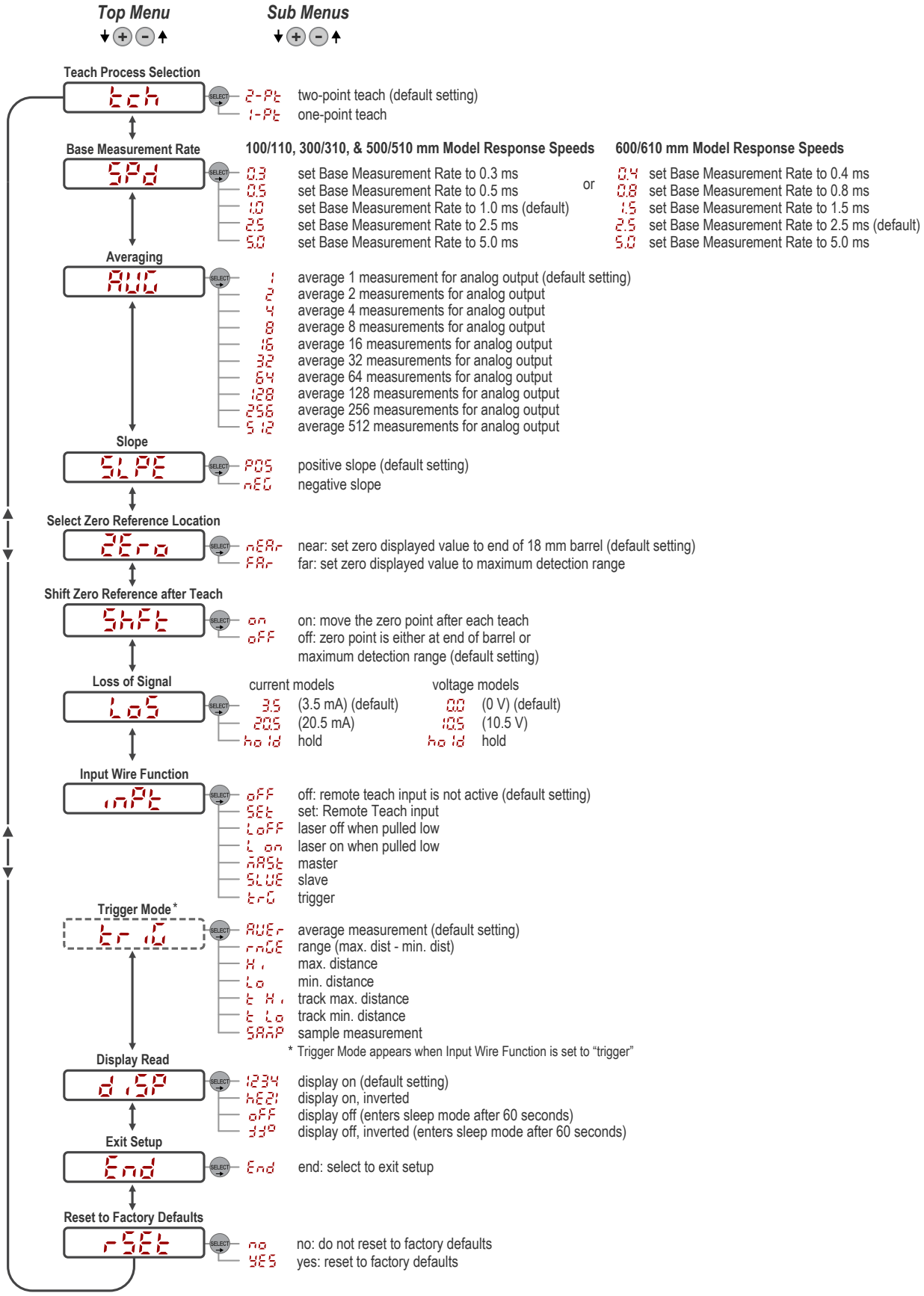
Setup Mode

1. Access Setup mode and the sensor menu from Run mode by pressing and holding **MODE** for longer than 2 seconds.
2. Use  and  to navigate through the menu.
3. Press **SELECT** to select a menu option and access the submenus.
4. Use  and  to navigate through the submenus.
5. Select a submenu option.
   - Press **SELECT** to select a submenu option and return to the top menu.
   - Press and hold **SELECT** for longer than 2 seconds to select a submenu option and return immediately to Run mode.

To exit Setup mode and return to Run mode, navigate to  and press SELECT.

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Sensor Menu Map



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TEACH Menu (tch)

Use this menu to select the TEACH mode. The default is two-point TEACH.

- 2-Pt —Two-point
- 1-Pt —One-point TEACH

After the TEACH mode is selected, from Run mode, press and hold **TEACH** for longer than 2 seconds to start the TEACH mode and program the sensor. See "TEACH Procedures " on page 29 for additional information and remote input TEACH instructions.

Base Measurement Rate (SPd)

Use this menu to select the base measurement rate. The total response speed depends upon the measurement rate setting and the averaging setting. See "Averaging (AVG)" on page 20 for more information.

- 0.3 —0.3 ms
- 0.5 —0.5 ms
- 1.0 —1.0 ms
- 2.5 —2.5 ms
- 5.0 —5.0 ms

Tradeoffs—Threaded Barrel Models

Base Measurement Rate (ms)	Base Measurement Rate in Sync Mode (ms)	Ambient Light Rejection	Excess Gain—90% white card			
			at 25 mm	at 100 mm	at 300 mm	at 600 mm
0.4	0.8	Disabled	560	220	50	12
0.8	1.6	Enabled	560	220	50	12
1.5	3.0	Enabled	2000 (720)	800 (300)	160 (60)	40 (14)
2.5	5.0	Enabled	4000 (2000)	1600 (800)	320 (160)	80 (40)
5.0	10.0	Enabled	8000 (4000)	3200 (1600)	640 (320)	160 (80)

Tradeoffs—Flush Mount Models

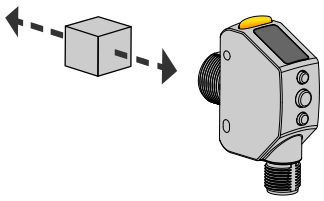
Base Measurement Rate (ms)	Base Measurement Rate in Sync Mode (ms)	Ambient Light Rejection	Excess Gain—90% white card			
			at 35 mm	at 110 mm	at 310 mm	at 610 mm
0.4	0.8	Disabled	560	220	50	12
0.8	1.6	Enabled	560	220	50	12
1.5	3.0	Enabled	2000 (720)	800 (300)	160 (60)	40 (14)
2.5	5.0	Enabled	4000 (2000)	1600 (800)	320 (160)	80 (40)
5.0	10.0	Enabled	8000 (4000)	3200 (1600)	640 (320)	160 (80)

Averaging (AVG)

Use this menu to set the number of measurements that are averaged together for the analog output. Increasing the averaging improves repeatability, but increases the total response speed. The default is 1. The filter can be set to 1, 2, 4, 8, 16, 32, 64, 128, 256, or 512. Use the table to determine the total response speed.

NOTE: The Q4X uses a dynamic measurement rate, so these response times are worst-case.

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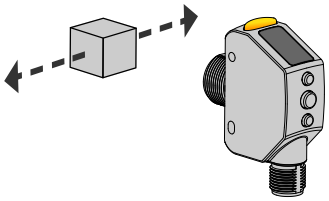
Response Speed for 100/110, 300/310, and 500/510 models

Base Measurement Rate	Filter Setting									
	1	2	4	8	16	32	64	128	256	512
0.3 ms	0.5 ms	0.75 ms	1.5 ms	4 ms	8 ms	15 ms	30 ms	60 ms	120 ms	240 ms
0.5 ms	0.5 ms	1 ms	2 ms	5 ms	10 ms	25 ms	50 ms	100 ms	200 ms	350 ms
1 ms	1 ms	3 ms	5 ms	10 ms	20 ms	40 ms	75 ms	150 ms	300 ms	600 ms
2.5 ms	2.5 ms	5 ms	10 ms	25 ms	45 ms	80 ms	160 ms	320 ms	640 ms	1280 ms
5 ms	5 ms	10 ms	20 ms	40 ms	80 ms	160 ms	320 ms	640 ms	1280 ms	2560 ms

Response Speed for 600/610 models

Base Measurement Rate	Filter Setting									
	1	2	4	8	16	32	64	128	256	512
0.4 ms	0.5 ms	1.2 ms	2.5 ms	7 ms	13 ms	25 ms	50 ms	100 ms	200 ms	400 ms
0.8 ms	0.8 ms	1.6 ms	3.5 ms	8 ms	16 ms	40 ms	80 ms	160 ms	320 ms	560 ms
1.5 ms	1.5 ms	4.5 ms	8 ms	15 ms	30 ms	60 ms	115 ms	225 ms	450 ms	900 ms
2.5 ms	2.5 ms	5 ms	10 ms	20 ms	40 ms	80 ms	160 ms	320 ms	640 ms	1300 ms
5 ms	5 ms	10 ms	20 ms	40 ms	80 ms	160 ms	320 ms	640 ms	1300 ms	2500 ms

When lateral entry needs to be considered, the lateral entry response is added to calculate the total response time.



Lateral Entry Response

Base Measurement Rate	Lateral Entry Response
0.4 ms	2 ms
0.8 ms	5 ms
1.5 ms	15 ms
2.5 ms	25 ms
5 ms	50 ms

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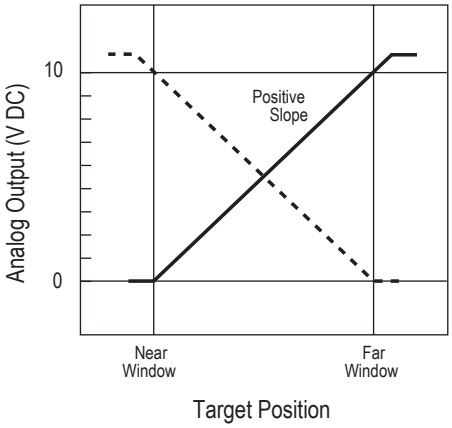
Slope (SLPE)

Use this menu to set the slope as positive or negative.

This swaps the 0 V and 10 V (4 and 20 mA) values. The default is positive. The slope is defined relative to the zero reference, so if the zero setting is changed from near to far, a slope will be considered positive if the analog output increases as the target becomes closer to the face of the sensor.

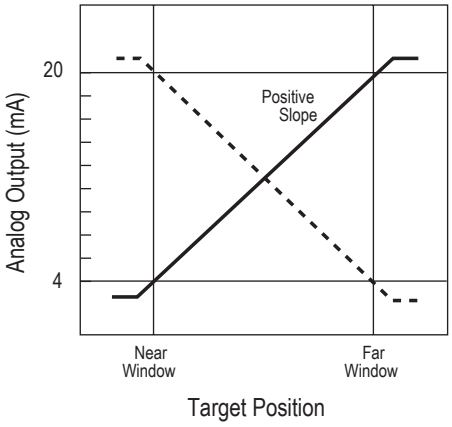
- **POS**—the slope is positive
- **nEG**—the slope is negative

Slope—Voltage Sourcing Models



The analog voltage output tracks slightly beyond the upper window limit (up to 10.2 V)

Slope—Current-Sourcing Models



The analog current output tracks slightly beyond each window limit (from 3.8 mA to 20.2 mA)

Zero Reference Location (ZEro)

Use this menu to select the zero-reference location. Changing the zero-reference location only affects the readout on the display and does not affect the output.

The default is **nEAr**, 0 = the front of the sensor.

- nEAr —0 is the front of the sensor and the measurement increases further from the sensor.
- FAr —0 is the maximum range and the measurement increases closer to the sensor.

Shift the Zero Reference Location after a TEACH (ShFt)

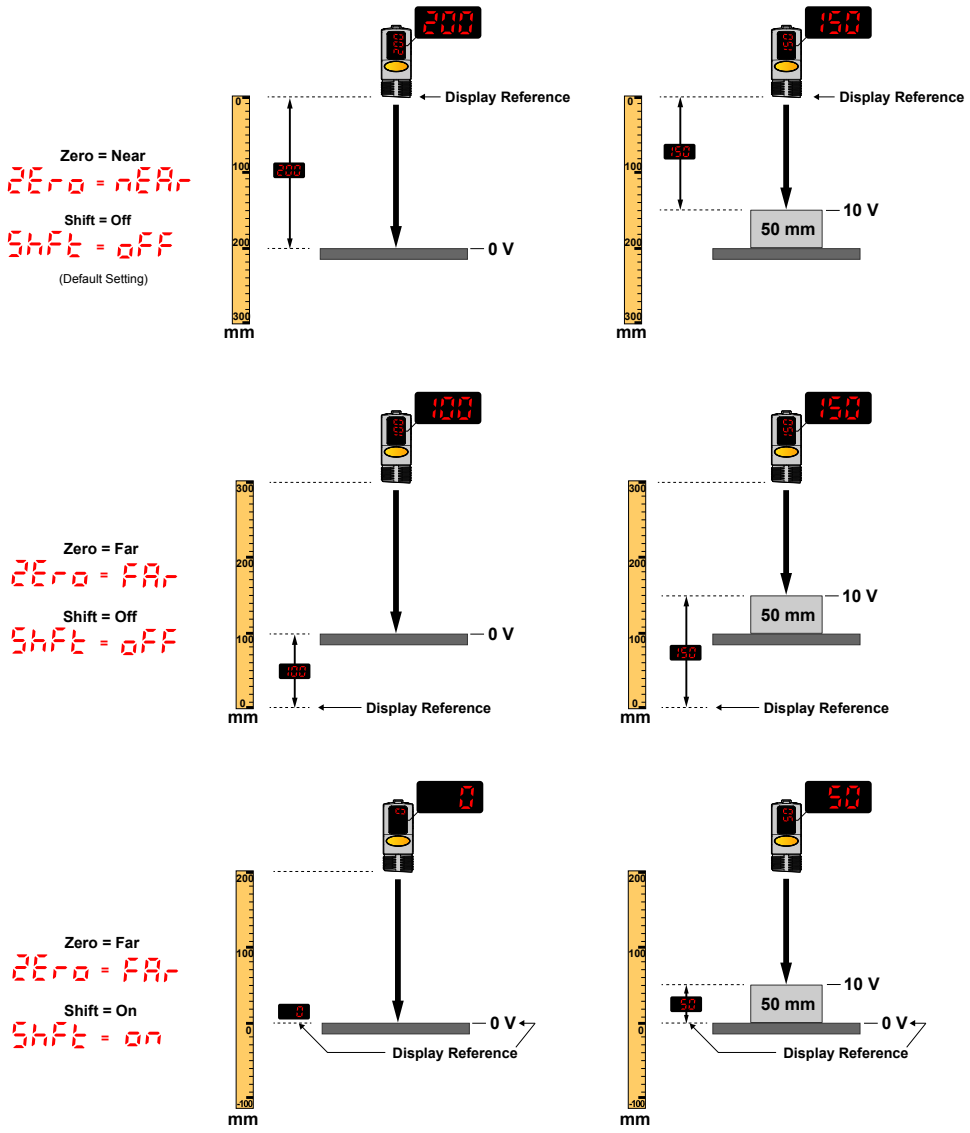
Use this menu to select whether the sensor shifts the zero reference location based on the last TEACH process. The default is oFF , 0 = the front of the sensor or the maximum range.

- on —Shift the zero reference location to one of the taught positions with each TEACH
- oFF —0 = the front of the sensor or the maximum range, depending on the ZEro setting

This figure illustrates three examples of how changes to the zero and shift settings affect what distance readout is shown on the display when in 2-pt TEACH mode. Changes to the zero setting affect the direction in which the distance increases. Turning the shift setting on sets the taught location as the reference point for any distance measurement. For two-point TEACH, this is the 0 V (4 mA) point. For one-point TEACH, this is the 5 V (12 mA) point.

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Example Zero and Shift settings



Loss of Signal (LOS)

Use this menu to select the Analog Output value used by the sensor during a loss of signal. When a signal is restored, measurement resumes. The default is 0 V (4 mA).

Analog output value during a loss of signal

Option	Description
0 V (4 mA)—default	The Analog Output switches to this value 2 seconds after a loss of signal. When advanced measurements are enabled, the Analog Output is updated to this value immediately upon the release of the trigger input.
10.5 V (20.5 mA)	The Analog Output switches to this value 2 seconds after a loss of signal. When advanced measurements are enabled, the Analog Output is updated to this value immediately upon the release of the trigger input.
Hold	The Analog Output holds the last value indefinitely during a loss of signal. When advanced measurements are enabled, the last value is held across the triggered measurement periods.

The Range advanced measurement behavior is affected by the Loss of Signal option. For additional information on advanced measurements, see "Trigger (trG)" on page 24. The Range advanced measurement tracks a maximum and a minimum during the measurement period, and calculates the range as follows:

Range = maximum distance – minimum distance

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If the maximum and/or minimum measurements are outside of the taught range values, the Loss of Signal option determines how the range is calculated.

Sensor behavior in range mode

Option	Description
0 V (4 mA)	If the maximum or minimum measurement is outside of the taught range values, the sensor outputs 0 V (4 mA) to indicate an out-of-range measurement.
10.5 V (20.5 mA)	If the maximum or minimum measurement is outside of the taught range values, the sensor outputs 10.5 V (20.5 mA) to indicate an out-of-range measurement.
Hold	The sensor limits the maximum and minimum measurements so that they cannot exceed the taught range values.

Input Wire Function (inPt)

Use this menu to select the input wire function. The default is off, ignore all remote input pulses.

- **oFF**—Ignore all remote input pulses
- **SEt**—Remote TEACH input
- **LoFF**—Laser off when pulled low
- **Lon**—Laser on when pulled low
- **nASt**—Master sync line output for two-sensor cross-talk avoidance
- **SLUE**—Slave sync line input for two-sensor cross-talk avoidance
- **trG**—Trigger mode for advanced measurements (see "Trigger (trG)" on page 24)

To configure sensors for master-slave operation, see "Sync Master/Slave " on page 32.

Trigger (trG)

The Trigger option sets the advanced measurement that is calculated when a trigger event is detected on the remote input.

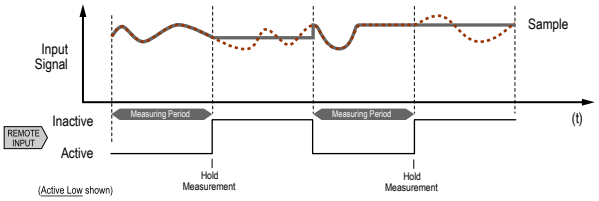
The analog output updates with the new advanced measurement on each trigger event. To use these Trigger options, the sensor Input Type option must be set to **trG**.

Trigger submenus

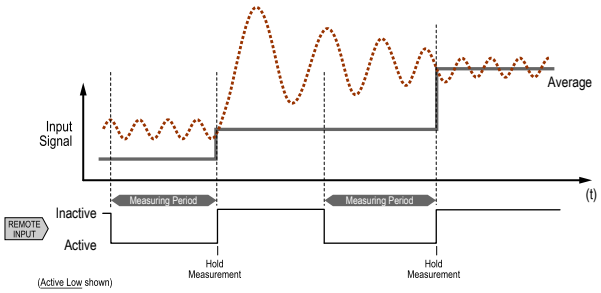
Trigger Submenus	Description
Average **AUEr**	The averaged distance since the last trigger event. (default)
Range **rnGE**	The difference between the maximum and minimum distance since the last trigger event. For additional information on the Range measurement behavior when the maximum or minimum distance is outside of the taught values, see "Loss of Signal (LOS)" on page 23.
Maximum **Hi**	The maximum distance since the last trigger event.
Minimum **Lo**	The minimum distance since the last trigger event.
TrackMax **t Hi**	The maximum distance since the last trigger event. The Analog Output tracks new maximum values during the measurement period.
TrackMin **t Lo**	The minimum distance since the last trigger event. The Analog Output tracks new minimum values during the measurement period.
Sample **SAnP**	The current distance at the time of the trigger event. The Analog Output tracks the sample values during the measuring period.

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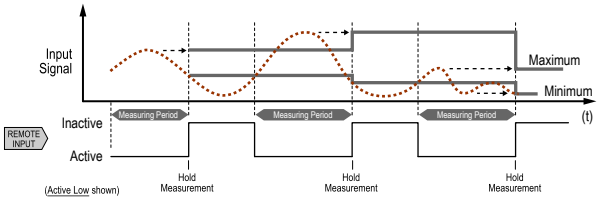
Sample



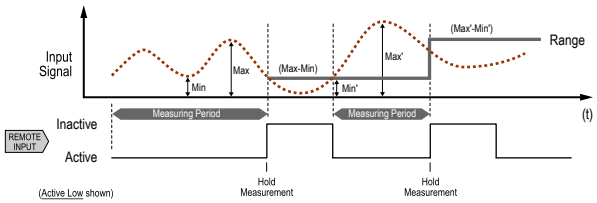
Average



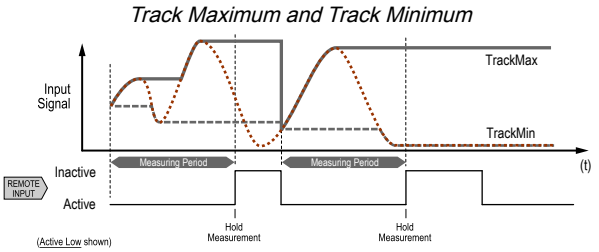
Maximum and Minimum



Range



Track Maximum and Track Minimum



Display View (diSP)

Use this menu to select the display view.

When the sensor is in sleep mode, the display wakes with the first button press.

- 1234 —Normal (default setting). When **1234** is inverted, the display is in inverted view model (rotated 180°).
- oFF —Normal and the display enters sleep mode after 60 seconds. When **oFF** is inverted, the display view is inverted (rotated 180°) and the display enters sleep mode after 60 seconds.

Exit Setup Mode (End)

Use this menu to end Setup mode.

Navigate to **End** and press **SELECT** to exit Setup mode and return to Run mode.

Reset to Factory Defaults (rSEt)

Use this menu to restore the sensor to the factory default settings.

- no —Select to return to the sensor menu without restoring the defaults.
- YES —Select to apply the factory defaults and return to Run mode.

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Factory Default Settings

Setting	Factory Default
Averaging (AVG)	1
Base Measurement Rate (SPd)	1—1 ms
Display View (d.SP)	1234—Normal, no sleep mode
Input Wire Function (inPt)	oFF—Ignore all remote input pulses If the sensor was reset using the remote input, the sensor remains in SEt mode to allow use of the remote input.
Loss of Signal (LOS)	00—0 V (4 mA)
Shift the Zero Reference Location after a TEACH (SHFt)	oFF—0 = the front of the sensor
Slope (SLPE)	POS—positive
TEACH Mode (tch)	2-Pt—Two-point TEACH
Zero Reference Location (zEro)	nEAr—Measurement increases further from sensor

Manual Adjustments

Manually adjust the distance set for the 0 V (4 mA) and 10 V (20 mA) values using the + and - buttons. The available adjustments vary depending on the TEACH mode selected.

Manual Adjustments in Two-Point TEACH Mode

Adjust the 10 V (20 mA) Point

1. From Run mode, press + to view and adjust the distance associated with the 10 V (20 mA) point. 10 U displays briefly, then the value slowly flashes indicating it can be changed.

   NOTE: If no changes are made within 8 seconds, the current distance value flashes quickly and the sensor returns to Run mode.

2. Press + to move the value up or - to move the value down.

   NOTE: If no additional changes are made within 4 seconds, the current distance value flashes quickly and the sensor returns to Run mode.

3. Press **Select** to confirm the new distance value. The new distance flashes rapidly, the new setting is accepted, and the sensor returns to Run mode.

Adjust the 0 V (4 mA) Point

1. Press - to view and adjust the distance associated with the 0 V (4 mA) point. 0 U flashes briefly, then the value flashes.

   NOTE: If no changes are made within 8 seconds, the current distance value flashes quickly and the sensor returns to Run mode.

2. Press + to move the value up or - to move the value down.

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> **NOTE:** If no additional changes are made within 4 seconds, the current distance value flashes quickly and the sensor returns to Run mode.

3. Press **Select** to confirm the new distance value. The new distance value flashes rapidly, the new setting is accepted, and the sensor returns to Run mode.

Manual Adjustments in One-Point TEACH Mode

Adjust the 5 V (12 mA) Midpoint

1. From Run mode, press + to view and adjust the distance setting associated with the 5 V (12 mA) midpoint (the mid point of the analog span). 5 U displays briefly, then the value slowly flashes indicating it can be changed.

> **NOTE:** If no changes are made within 8 seconds, the current distance value flashes quickly and the sensor returns to Run mode.

2. Press + to move the midpoint up or - to move the midpoint down.

> **NOTE:** If no additional changes are made within 4 seconds, the current distance value flashes quickly and the sensor returns to Run mode.

3. Press **Select** to confirm the new midpoint. The new midpoint value flashes rapidly, the new setting is accepted, and the sensor returns to Run mode.

Adjust the Analog Window Size

1. Press - to view and adjust the SPAN (the analog window size). SPAn flashes briefly, then the value flashes.
2. Press + to increase the size of the analog window or - to decrease the size of the analog window.
3. Press **Select** to confirm the window size. The new window size flashes rapidly, the new setting is accepted, and the sensor returns to Run mode.

Remote Input

Use the remote input to program the sensor remotely.

The remote input provides limited programming options and is Active low.

For Active low, connect the gray input wire to ground (0 V DC), with a remote switch connected between the wire and ground.

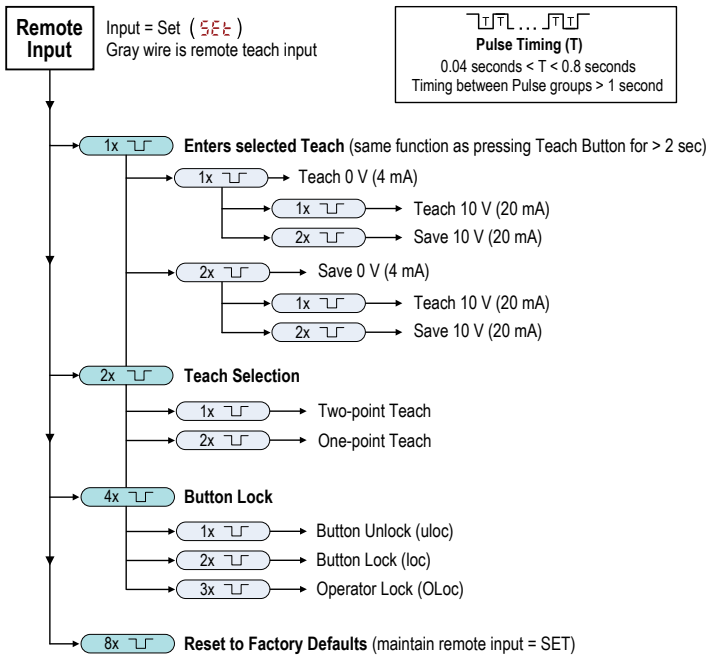
Pulse the remote input according to the diagram and the instructions provided in this manual.

The length of the individual programming pulses is equal to the value **T: 0.04 seconds ≤ T ≤ 0.8 seconds**.

Exit remote programming modes by setting the remote input low for longer than 2 seconds.

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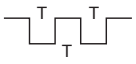
Remote Input Map



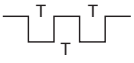
Select the TEACH Mode Using the Remote Input

Follow the instructions below to choose a specific TEACH Mode using Remote Input.

1. Access the TEACH selection.

Action		Result
Double-pulse the remote input.		**tch** displays.

2. Select the desired TEACH mode.

Action			Result
Pulses		**TEACH Mode**	
1		Two-point TEACH	The selected TEACH method displays for a few seconds and the sensor returns to Run mode.
2		One-point TEACH	

Reset to Factory Defaults Using the Remote Input

Follow the instructions below to reset the Q4X to factory defaults using Remote Input.

Eight-pulse the remote input to apply the factory defaults and return to Run mode.

The input wire function remains at remote teach input (**SEt**).

Locking and Unlocking the Sensor Buttons

Use the lock and unlock feature to prevent unauthorized or accidental programming changes.

Three settings are available:

- uLoc —The sensor is unlocked and all settings can be modified (default).
- Loc —The sensor is locked and no changes can be made.

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- 0Loc —The value associated with 0 V (4 mA) and 10 V (20 mA) can be changed by teaching or manual adjustment, but no sensor settings can be changed through the menu.

When in **Loc** mode, **Loc** displays when the **(SELECT)(TEACH)** button is pressed. The analog point displays when **(+)(DISP)** or **(-)(MODE)** are pressed, but **Loc** displays if the buttons are pressed and held.

When in **0Loc** mode, **Loc** displays when **(+)(DISP)** or **(-)(MODE)** are pressed and held. To access the manual adjust options, briefly press and release **(+)(DISP)** or **(-)(MODE)**. To enter TEACH mode, press the **(SELECT)(TEACH)** button and hold for longer than 2 seconds.

Button Instructions

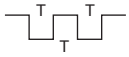
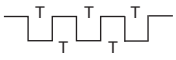
To enter **Loc** mode, hold **+** and press **-** four times. To enter **0Loc** mode, hold **+** and press **-** seven times. Holding **+** and pressing **-** four times unlocks the sensor from either lock mode and the sensor displays **uLoc**.

Remote Input Instructions

1. Access the remote input.

Action		Result
Four-pulse the remote input.		The sensor is ready to have the button state defined and **btn** displays.

2. Lock or unlock the sensor buttons.

Action		Result
Single-pulse the remote input to unlock the sensor.		**uLoc** displays and the sensor returns to Run mode.
Double-pulse the remote input to lock the sensor.		**Loc** displays and the sensor returns to Run mode.
Triple-pulse the remote input to apply the operator lock to the sensor		**0Loc** displays and the sensor returns to Run mode

TEACH Procedures

Use the following procedures to teach the sensor.

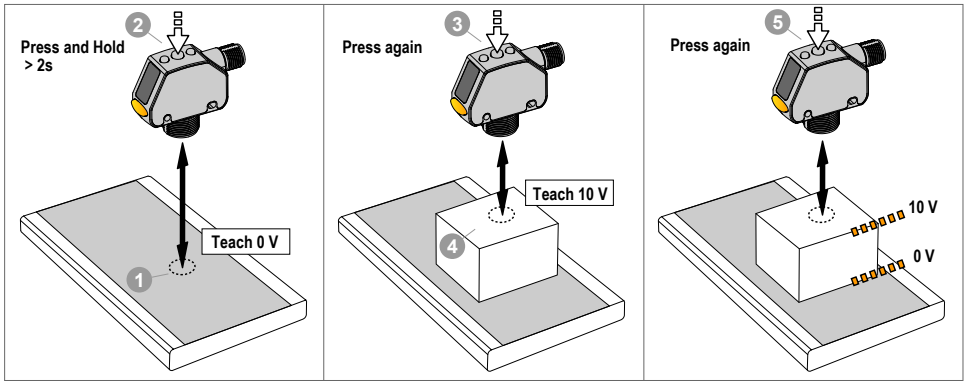
To cancel a TEACH procedure, press **TEACH** for longer than 2 seconds, or hold the remote input low for longer than 2 seconds. **CnCL** momentarily displays when a TEACH procedure is canceled.

Two-Point TEACH (2-Pt)

Two-point TEACH sets the distance values associated with 0 V and 10 V (4 mA and 20 mA) based on taught target distances.

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Two-Point TEACH



NOTE: The sensor must be set to tCh = 2-Pt to use the following instructions.

NOTE: To program the sensor using remote input, remote input must be enabled (rmPt = SEt).

1. Present the target.

Method	Action	Result
Push Button	Present the first target. The sensor-to-target distance must be within the sensor's range.	The target's measurement value displays.
Remote Input		

2. Start the TEACH mode.

Method	Action		Result
Push Button	Press and hold **TEACH** for longer than 2 seconds.		SEt and 0 V flash alternately on the display. The 2-Pt indicator flashes.
Remote Input	Single-pulse the remote input.		

3. Teach the sensor.

Method	Action		Result
Push Button	Press **TEACH** to teach the target.		The measurement value flashes briefly, and the sensor is taught the first target. SEt and 10 V flash alternately on the display. The 2-Pt indicator flashes.
Remote Input	Single-pulse the remote input.		

It is possible to skip teaching the 0 V (4 mA) point and continue to use the existing setting. When using the push button, hold − for four seconds. The sensor displays SAVE and then flashes the existing value. When using the remote input, double-pulse the remote input.

4. Present the target.

Method	Action	Result
Push Button	Present the second target. The sensor-to-target distance must be within the sensor's range.	SEt and 10 V flash alternately on the display. The 2-Pt indicator flashes.
Remote Input		

5. Teach the sensor.

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Method	Action		Result
Push Button	Press **TEACH** to teach the target.		The new switch point flashes rapidly and the sensor returns to Run mode.
Remote Input	Single-pulse the remote input.		

NOTE: If the same target is taught both times, Lo and SPAn flash alternately on the display, the 10 V (20 mA) value is automatically adjusted to maintain the minimum window size, the new distance quickly flashes four times, and the sensor returns to Run mode.

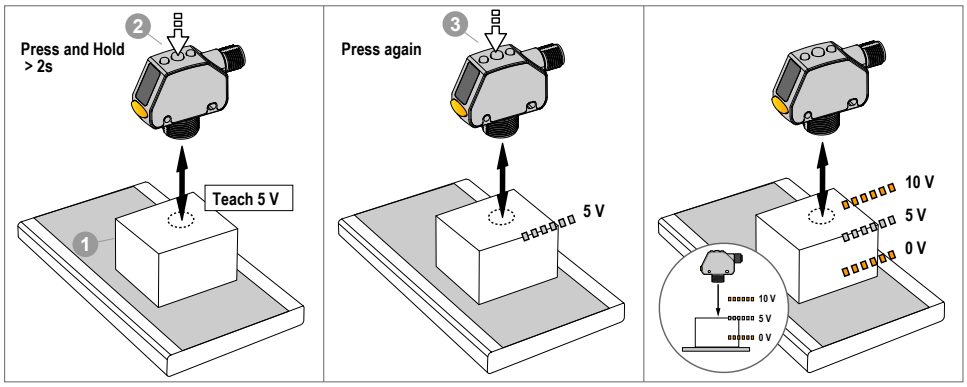
It is possible to skip teaching the 10 V (20 mA) point and continue to use the existing setting. When using the push button, hold − for four seconds. The sensor displays SAVE and then flashes the existing value. When using the remote input, double-pulse the remote input.

One-Point TEACH (1-Pt)

One-point TEACH mode defines the span of the analog output. One-point TEACH also defines the 5 V (12 mA) midpoint of the analog output to center the analog output around a reference target position.

Refer to "Manual Adjustments in One-Point TEACH Mode " on page 27 for more information.

One-Point Window



NOTE: The sensor must be set to tch = 1-Pt to use the following instructions.

NOTE: To program the sensor using remote input, remote input must be enabled (rmPt = SEt).

1. Present the target.

Method	Action	Result
Push Button	Present the first target. The sensor-to-target distance must be within the sensor's range.	The target's measurement value displays.
Remote Input		

2. Start the TEACH mode.

Method	Action		Result
Push Button	Press and hold **TEACH** for longer than 2 seconds.		SEt and 5 U flash alternately on the display. The 1-Pt indicator flashes.
Remote Input	No action required.		N/A

3. Teach the sensor.

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Method	Action		Result
Push Button	Press **TEACH** to teach the target.		The measurement value flashes briefly, and the sensor returns to Run mode.
Remote Input	Single-pulse the remote input.		

Sync Master/Slave

Two Q4X sensors may be used together in a single sensing application.

To eliminate crosstalk between the two sensors, configure one sensor to be the master and one to be the slave. In this mode, the sensors alternate taking measurements and the response speed doubles.

> **IMPORTANT:** The master sensor and the slave sensor must be programmed for the same Base Response Speed setting. The master sensor and slave sensor must share a common power source.

1. Configure the first sensor as the master; navigate to: **inPt › nASt**.
2. Configure the second sensor as the slave; navigate: **inPt › SLUE**.
3. Connect the gray (input) wires of the two sensors together.

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Chapter Contents

Chapter 5 Abbreviations

The following table describes the abbreviations used on the sensor display and in this manual.

Abbreviation	Description
----	No valid signal in range
1-Pt	One-point TEACH
2-Pt	Two-point TEACH
AUG	Average—Trigger output of Average measurement value
bot	Bottom
btn	Button
CnCL	Cancel
d.SP	Display read
d.St	Distance
End	End—exit the sensor menu
FAr	Far zero reference location—the maximum range is 0 and the measurement increase as the target moves closer to the sensor
FLtr	Filter
H.	Trigger output of maximum measurement value
HoLd	Hold the last value
inPt	Input wire function
Lo	Trigger output of minimum measurement value
Loc	Lock/locked
LoFF	Laser off
LOS	Loss of signal
mA	milliAmp
mASt	Master
M in	Min
nEAr	Near zero reference location—the end of the barrel is 0 and the measurement increase as the target moves further away from the sensor
nEG	Negative slope
OLoc	Allows teaching and adjusting 0 V and 10 V (4 mA and 20 mA) settings, while locking out access to other sensor settings.
POS	Positive slope

Continued on page 34

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Continued from page 33

Abbreviation	Description
rnGE	Range—Hi to Lo
rSEt	Reset to factory defaults
SAmP	Sample—Trigger output of a sampled measurement value
SEt	Input wire = remote teach function
ShFt	Shift the Zero Reference Location after a TEACH
SLUE	Slave
SPAn	Span—analog window size
SPd	Response speed
tch	TEACH process selection
t Hi	Trigger setting for tracking maximum measurement value
t Lo	Trigger setting for tracking minimum measurement value
trG	Trigger
tr iG	Trigger—Set the trigger type
U	Volt
uLoc	Unlock/unlocked
uuuu	Saturated signal (too much light)
ZEro	Zero—select the zero reference location

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Chapter Contents

Chapter 6 Troubleshooting

Troubleshooting Codes

Code	Description	Resolution
----	No valid signal in range	Reposition the sensor or the target
LoSPAn	The adjusted or taught window size is smaller than the minimum window size.	The sensor automatically adjusts the window size to maintain the minimum window and completes the adjustment or the TEACH
rnGE	The distance being taught is outside of the valid sensing range	Present a target within the sensor's range and re-TEACH.
uuuu	The signal is saturated (too much light)	Reposition the sensor or the target to increase the detection distance, or increase the angle of incidence between the sensor and the target
End	The adjusted or taught end point is between the other end point and the end of range. There is insufficient space to create the minimum window size.	TEACH or adjust the end points to maintain the minimum window size within the sensing range.

Error Codes

Code	Description	Resolution
ErrE	EEPROM fault	Contact Banner Engineering to resolve
ErrL	Laser fault	Contact Banner Engineering to resolve
ErrC	Output short-circuited	Check the wiring for an electrical short circuit and to ensure that the wiring is correct
Err5	System fault	Contact Banner Engineering to resolve

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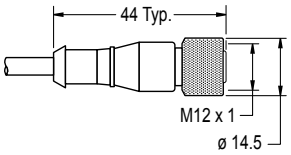
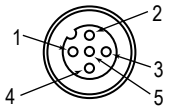
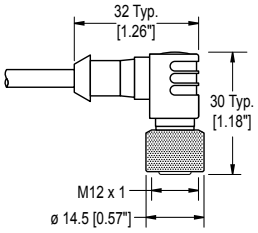
Cordsets 36
Brackets 38
Aperture Kits—Threaded Barrel Models 39

Chapter 7 Accessories

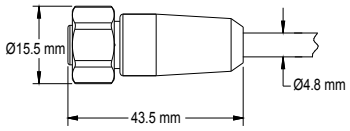
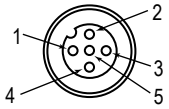
Cordsets

All measurements are listed in millimeters, unless noted otherwise. The measurements provided are subject to change.

Standard Cordsets

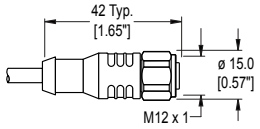
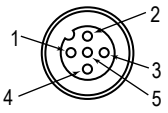
5-Pin Single-Ended M12 Female Shielded Cordsets				
Model	**Length**	**Style**	**Dimensions**	**Pinout (Female)**
MQDEC2-506	2 m (6.56 ft)	Straight		 1 = Brown 2 = White 3 = Blue 4 = Black 5 = Gray c UL us
MQDEC2-515	5 m (16.4 ft)			
MQDEC2-530	9 m (29.5 ft)			
MQDEC2-550	15 m (49.2 ft)			
MQDEC2-575	23 m (75.44 ft)			
MQDEC2-5100	30.5 m (100 ft)			
MQDEC2-506RA	2 m (6.56 ft)	Right-Angle		
MQDEC2-515RA	5 m (16.4 ft)			
MQDEC2-530RA	9 m (29.5 ft)			
MQDEC2-550RA	15 m (49.2 ft)			
MQDEC2-575RA	23 m (75.44 ft)			
MQDEC2-5100RA	31 m (101.68 ft)			

5-Pin Threaded M12 Cordsets—Washdown Stainless Steel

5-Pin Single-Ended M12 Female Stainless Steel Washdown Cordsets				
Model	**Length**	**Style**	**Dimensions**	**Pinout (Female)**
MQDC-WDSS-0506	2 m (6.56 ft)	Straight		 1 = Brown 2 = White 3 = Blue 4 = Black 5 = Gray
MQDC-WDSS-0515	5 m (16.4 ft)			
MQDC-WDSS-0530	9 m (29.5 ft)			

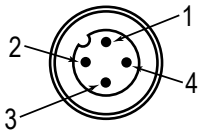
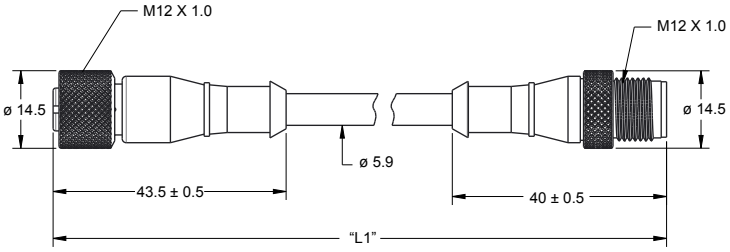
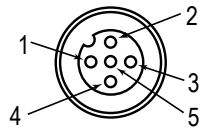
5-Pin Threaded M12 Cordsets—Washdown, with Shield

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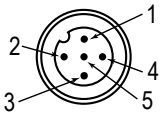
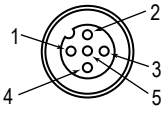
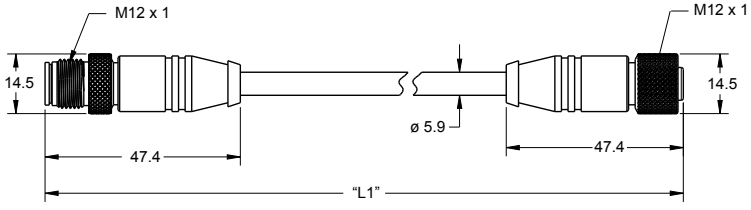
5-Pin Single-Ended M12 Female Washdown, Shielded Cordsets				
Model	**Length**	**Style**	**Dimensions**	**Pinout (Female)**
MQDCWD-506	2 m (6.56 ft)	Straight		 1 = Brown 2 = White 3 = Blue 4 = Black 5 = Gray
MQDCWD-530	9 m (29.5 ft)			

4-Pin Female and 5-Pin Male Threaded M12 Cordset—Double Ended

Cable: PVC jacket, PUR (polyurethane) connector body, nickel-plated brass coupling nut
Conductors: 20 AWG; No Shield

Double-Ended 5-pin M12 Female to 4-Pin M12 Male Cordsets				
Model	**Length "L1"**	**Style**	**Pinout**	
MQDC-5401SS	0.30 m (0.98 ft)	Female Straight / Male Straight	Male 	1 = Brown 2 = White 3 = Blue 4 = Black
MQDC-5406SS	1.83 m (6.00 ft)			
			Female 	1 = Brown 2 = Not Used 3 = Blue 4 = Black 5 = White

5-Pin Male Threaded and 5-Pin Female Quick Disconnect M12 Cordset with Shield—Double Ended

5-Pin Double-Ended M12 Female to M12 Male Shielded Cordset				
Model	**Length "L1"**	**Style**	**Pinout (Male)**	**Pinout (Female)**
MQDEC3-503SS	0.91 m (2.99 ft)	Female Straight/Male Straight		
MQDEC3-506SS	1.83 m (6 ft)			
MQDEC3-515SS	4.58 m (15 ft)			
MQDEC3-530SS	9.2 m (30.2 ft)			
			1 = Brown 2 = White 3 = Blue	4 = Black 5 = Gray

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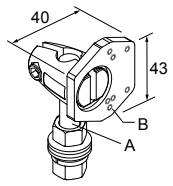
Brackets

All measurements are listed in millimeters, unless noted otherwise. The measurements provided are subject to change.

SMBQ4X..

- Swivel bracket with tilt and pan movement for precision adjustment
- Easy sensor mounting to extruded rail T-slots
- Metric and inch size bolts are available
- Side mounting of some sensors with the 3 mm screws included with the sensor

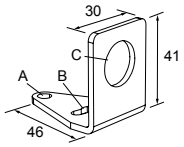
B = 7 × M3 × 0.5
Bolt thread (A): 3/8 - 16 × 2¼ in for SMBQ4XFA; M10 - 1.5 × 50 for SMBQ4XFAM10; n/a; no bolt included. Mounts directly to 12 mm (½ in) rods for SMBQ4XFMA1



SMB18A

- Right-angle mounting bracket with a curved slot for versatile orientation
- 12-ga. stainless steel
- 18 mm sensor mounting hole
- Clearance for M4 (#8) hardware

Hole center spacing: A to B = 24.2
Hole size: A = ø 4.6, B = 17.0 × 4.6, C = ø 18.5



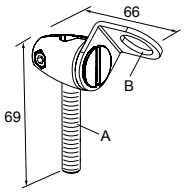
SMB18FA..

- Swivel bracket with tilt and pan movement for precision adjustment
- Easy sensor mounting to extruded rail T-slots
- Metric and inch size bolts available
- 18 mm sensor mounting hole

Hole size: B=ø 18.1

Bolt Thread (A):

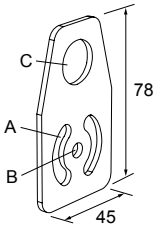
SMB18FA = 3/8 - 16 × 2 in
SMB18FAM10 = M10 - 1.5 × 50
SMB18FAM12 = n/a; no bolt included. Mounts directly to 12 mm (½ in) rods



SMBAMS18P

- Flat SMBAMS series bracket with 18 mm hole
- Articulation slots for 90+° rotation
- 12-ga. (2.6 mm) cold-rolled steel

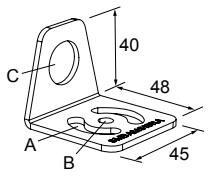
Hole center spacing: A = 26.0, A to B = 13.0
Hole size: A = 26.8 × 7.0, B = ø 6.5, C = ø 19.0



SMBAMS18RA

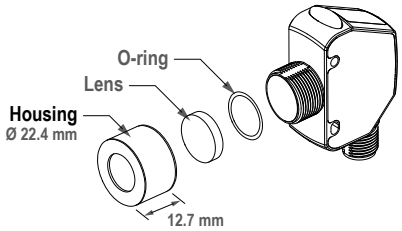
- Right-angle SMBAMS series bracket with 18 mm hole
- Articulation slots for 90+° rotation
- 12-ga. (2.6 mm) cold-rolled steel

Hole center spacing: A = 26.0, A to B = 13.0
Hole size: A = 26.8 × 7.0, B = ø 6.5, C = ø 19.0



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Aperture Kits—Threaded Barrel Models



APG18S	
Kit with glass lens to protect plastic sensor lens from chemical environments and weld splatter damage. Used with S18, M18, T18, TM18, and Q4X	

Additional Information

- Borosilicate glass window protects the PMMA window from weld splatter and chemicals
- Adds 4.8 mm to the length of the threaded barrel
- Reduces excess gain by 30%; increase the response time to restore excess gain

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Chapter 8 Product Support and Maintenance

Clean Sensor with Compressed Air and Water

Handle the sensor with care during installation and operation. Sensor windows soiled by fingerprints, dust, water, oil, etc. create stray light that may degrade the peak performance of the sensor.

Blow the window clear using filtered, compressed air, then clean as necessary using only water and a lint-free cloth. Do not use any other chemicals for cleaning.

Contact Us

Banner Engineering Corp. headquarters is located at: 9714 Tenth Avenue North | Plymouth, MN 55441, USA | Phone: + 1 888 373 6767

For worldwide locations and local representatives, visit www.bannerengineering.com.

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